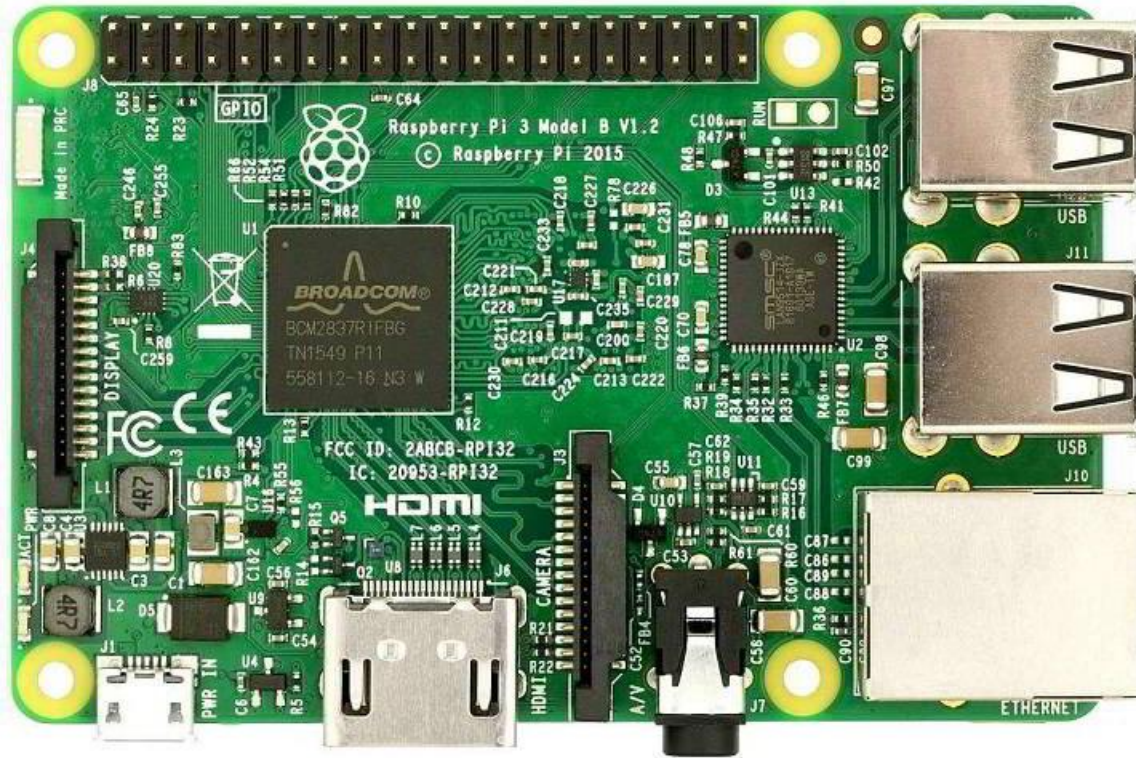


# Introduction to Raspberry Pi and It's Programming



**Resource Person**

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# What is Raspberry Pi?

- Raspberry Pi is a **small single board computer**. By connecting peripherals like Keyboard, mouse, display to the Raspberry Pi, it will act as a **mini personal computer**.
- Raspberry Pi is popularly used for **real time Image/Video Processing, IoT based applications and Robotics applications**.
- Raspberry Pi is **slower than laptop or desktop** but is still a computer which can provide all the expected features or abilities, at a **low power consumption**.

# OS for Raspberry Pi

- Raspberry Pi Foundation officially provides **Debian based Raspbian OS**. Also, they provide **NOOBS OS** for Raspberry Pi.
- We can install several **Third-Party versions** of OS like Ubuntu, Archlinux, RISC OS, Windows 10 IOT Core, etc.
- **Raspbian OS** is official Operating System available for free to use. This OS is efficiently optimized to use with Raspberry Pi. Raspbian have GUI which includes tools for Browsing,

# Raspberry Pi Processor

- It has ARM based **Broadcom Processor SoC** along with **on-chip GPU** (Graphics Processing Unit).
- The CPU speed of Raspberry Pi varies from **700 MHz to 1.2 GHz**. Also, it has on-board SDRAM that ranges from **256 MB to 1 GB**.
- Raspberry Pi also provides **on-chip SPI, I2C, and UART modules**.

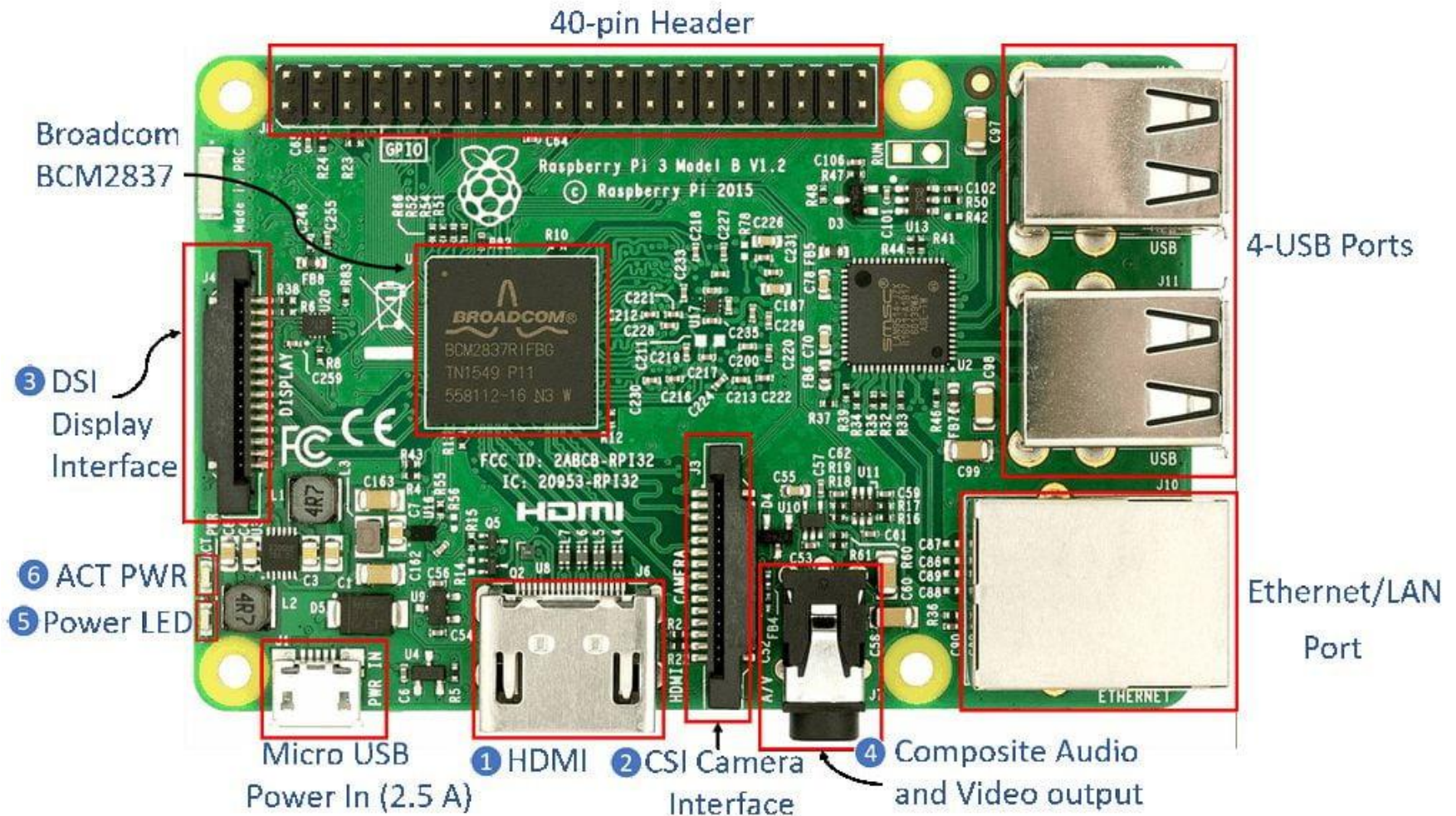
# **Versions of Raspberry Pi Models**

There are different versions of raspberry pi available as listed below:

- **Raspberry Pi 1 Model A**
- **Raspberry Pi 1 Model A+**
- **Raspberry Pi 1 Model B**
- **Raspberry Pi 1 Model B+**
- **Raspberry Pi 2 Model B**
- **Raspberry Pi 3 Model B**
- **Raspberry Pi 4 Model B**
- **Raspberry Pi Zero**



# Raspberry Pi 3 Hardware Details



# Raspberry Pi 3 Hardware Details

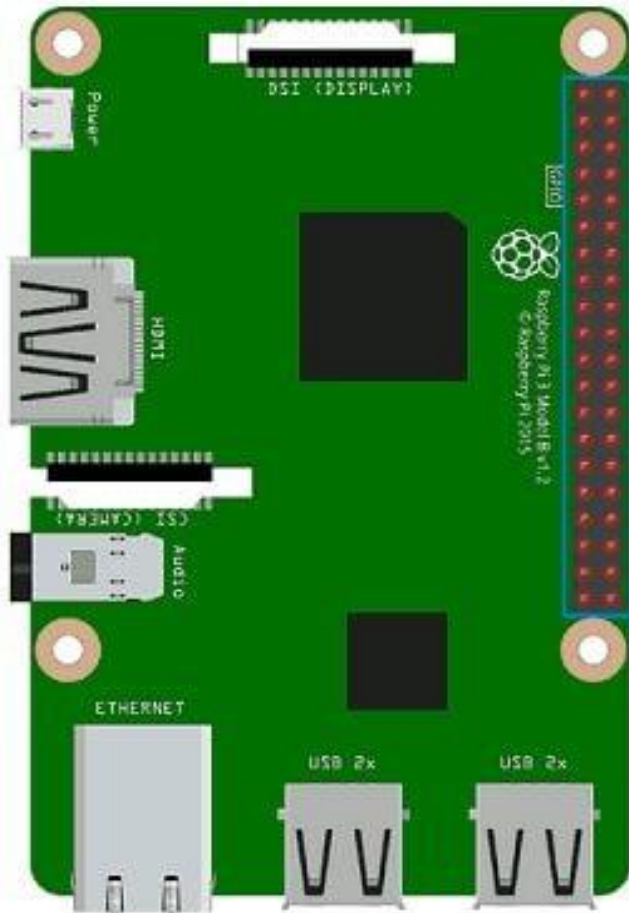
- **HDMI (High-Definition Multimedia Interface):** It is used for transmitting uncompressed video or digital audio data to the Computer Monitor, Digital TV, etc. Generally, this HDMI port helps to connect Raspberry Pi to the Digital television.
- **CSI Camera Interface:** CSI (Camera Serial Interface) interface provides a connection in between Broadcom Processor and Pi camera. This interface provides electrical connections between two devices.
- **DSI Display Interface:** DSI (Display Serial Interface) Display Interface is used for connecting LCD to the Raspberry Pi using 15-pin ribbon cable. DSI provides fast High-resolution display interface specifically used for sending video data directly from GPU to the LCD display.

# Raspberry Pi 3 Hardware Details

- **Composite Video and Audio Output:** The composite Video and Audio output port carries video along with audio signal to the Audio/Video systems.
- **Power LED:** It is a RED colored LED which is used for Power indication. This LED will turn ON when Power is connected to the Raspberry Pi. It is connected to 5V directly and will start blinking whenever the supply voltage drops below 4.63V.
- **ACT PWR:** ACT PWR is Green LED which shows the SD card activity.



# Raspberry Pi GPIO Access



3.3V	1	2	5V
GPIO2 (SDA1)	3	4	5V
GPIO3 (SCL1)	5	6	GND
GPIO4 (GPIO_GCLK)	7	8	GPIO14 (UART_TXD0)
GND	9	10	GPIO15 (UART_RXD0)
GPIO17 (GPIO_GEN0)	11	12	GPIO18 (GPIO_GEN1)
GPIO27 (GPIO_GEN2)	13	14	GND
GPIO22 (GPIO_GEN3)	15	16	GPIO23 (GPIO_GEN4)
3.3V	17	18	GPIO24 (GPIO_GEN5)
GPIO10 (SPI0_MOSI)	19	20	GND
GPIO9 (SPI0_MISO)	21	22	GPIO25 (GPIO_GEN6)
GPIO11 (SPI0_CLK)	23	24	GPIO8 (SPI_CE0_N)
GND	25	26	GPIO7 (SPI_CE1_N)
ID_SD (I2C EEPROM)	27	28	ID_SC (I2C EEPROM)
GPIO5	29	30	GND
GPIO6	31	32	GPIO12
GPIO13	33	34	GND
GPIO19	35	36	GPIO16
GPIO26	37	38	GPIO20
GND	39	40	GPIO21



# Raspberry Pi GPIO Access

GPIO (General Purpose Input Output) pins can be used as input or output and allows raspberry pi to connect with general purpose I/O devices.

- Raspberry pi 3 model B took out **26 GPIO pins** on board.
- Raspberry pi can **control many external I/O devices** using these GPIO's.
- These pins are a **physical interface** between the Pi and the outside world.
- We can program these pins according to our needs to interact with external devices.
- Raspberry Pi can **connect to the Internet** using Ethernet port or on-board Wi-Fi adapter.

# Pin Numbering

We should define GPIO pin which we want to use as an output or input. But Raspberry Pi has **two ways of defining pin number** which are as follows:

- **GPIO Numbering**
- **Physical Numbering**

# GPIO Numbering

- In **GPIO Numbering**, pin number refers to number on Broadcom SoC (System on Chip) channel (**BCM**). So, we should always consider the pin mapping for using GPIO pin. GPIO Numbering (BCM) is defined as

**GPIO.setmode(GPIO.BCM)**

# Physical Numbering

- While in **Physical Numbering**, pin number refers to the pin of 40-pin P1 header on Raspberry Pi **Board**. The above physical numbering is simple as we can count pin number on P1 header and assign it as GPIO. Physical Numbering (Board) is defined as

**GPIO.setmode(GPIO.BOARD)**

# Libraries Generally Used

## 1) RPi.GPIO

- **Overview:** Provides low-level control of GPIO pins.
- **Key Features:**
  - Configure pin modes (input/output).
  - Control digital signals (high/low).
  - Event detection (button presses).
- **Use Case:** Low-level hardware control (LEDs, sensors).
- **Code Example:**

```
import RPi.GPIO as GPIO
GPIO.setmode(GPIO.BCM)
GPIO.setup(18, GPIO.OUT)
GPIO.output(18, GPIO.HIGH)
```



# Libraries Generally Used

## 2) time

- **Overview:** The time library provides various time-related functions.
- **Key Functions:**
  - `time.time()`: Returns current time in seconds since the epoch.
  - `time.sleep()`: Pauses execution for a specified number of seconds.
  - `time.strftime()`: Formats time into a readable string.
  - `time.localtime()`: Returns the current local time.
- **Use Case Example:** Delay execution to control timing of hardware events.
- **Eg. `time.sleep(1)`**

# Libraries Generally Used

## 3) picamera

- **Overview:** picamera allows for interfacing with the Raspberry Pi camera module.
- **Key Features:**
  - Capture still images and video.
  - Real-time video stream handling.
  - Controlling camera properties like brightness, contrast, etc.
- **Use Case Example:** Capturing images for a security system or time-lapse photography.
- **Code Example:**

```
from picamera import PiCamera  
camera = PiCamera()  
camera.capture('image.jpg')
```

# Libraries Generally Used

## 4) GPIOZero Library

- **Overview:** gpiozero is used for controlling the GPIO pins on the Raspberry Pi.
- **Key Features:**
  - Control LEDs, buttons, motors, and other components.
  - Provides a simple interface for hardware control.
- **Use Case Example:** Automating home appliances using GPIO pins.
- **Code Example:**

```
from gpiozero import LED
```

```
led = LED(17)
```

```
led.on()
```

# Libraries Generally Used

## 5) Adafruit\_DHT Library

- **Overview:** The Adafruit\_DHT library is used to interface with DHT11/DHT22 humidity and temperature sensors.
- **Key Features:**
  - Retrieve temperature and humidity data from the sensor.
  - Supports multiple sensor types (DHT11, DHT22).
- **Use Case Example:** Home automation and weather stations.
- **Code Example:**

```
import Adafruit_DHT
sensor = Adafruit_DHT.DHT22
humidity, temperature =
```

# Libraries Generally Used

## 6) Serial Library

- **Overview:** The serial library enables serial communication with devices connected to the Raspberry Pi via UART or USB.
- **Key Features:**
  - Send and receive data over serial communication.
  - Configure baud rate, timeout, and port settings.
- **Use Case Example:** Communicating with Arduino or other microcontrollers.
- **Code Example:**

```
import serial
```

```
ser = serial.Serial('/dev/ttyUSB0', 9600)
```

```
ser.write(b'Hello!')
```

# Libraries Generally Used

## 7) Math Library

- **Overview:** The math library provides mathematical functions.
- **Key Functions:**
  - `math.sqrt()`: Square root.
  - `math.pi`: Constant Pi.
  - `math.sin()`, `math.cos()`, `math.tan()`: Trigonometric functions.
- **Use Case Example:** Perform calculations in robotic control systems.
- **Code Example:**

```
import math
```

```
result = math.sqrt(16)
```

# Functions Used

## 1) **GPIO.setmode (Pin Numbering System)**

- This function is used to define Pin numbering system i.e. GPIO numbering or Physical numbering.

In BCM,

**GPIO.setmode(GPIO.BCM)**

**GPIO.setup(21, GPIO.OUT)**

In BOARD,

**GPIO.setmode(GPIO.BOARD)**

**GPIO.setup(40, GPIO.OUT)**



# Functions Used

## 2) `GPIO.setwarnings(False)`

- When we initialize any GPIO pin it shows warning while compiling because of previous initialization of same pin.
- To avoid this warning, we should disable warnings using command

## `GPIO.setwarnings(False)`

# Functions Used

## 3) GPIO.setup (channel, direction, initial value, pull up/pull down)

This function is used to set the direction of GPIO pin as an input/output.

- channel - GPIO pin number as per numbering system.
- direction - set direction of GPIO pin as either Input or Output.
- initial value - can provide initial value
- pull up/pull down - enable pull up or pull down if required

# Functions Used

## 3) **GPIO.setup (channel, direction, initial value, pull up/pull down)**

Few examples are given as follows,

- GPIO as Output

**GPIO.setup(channel, GPIO.OUT)**

- GPIO as Input

**GPIO.setup(channel, GPIO.IN)**

- GPIO as Output with initial value

**GPIO.setup(channel, GPIO.OUT, initial=GPIO.HIGH)**

- GPIO as Input with Pull up resistor

**GPIO.setup(channel, GPIO.IN, pull\_up\_down =  
GPIO.PUD\_UP)**

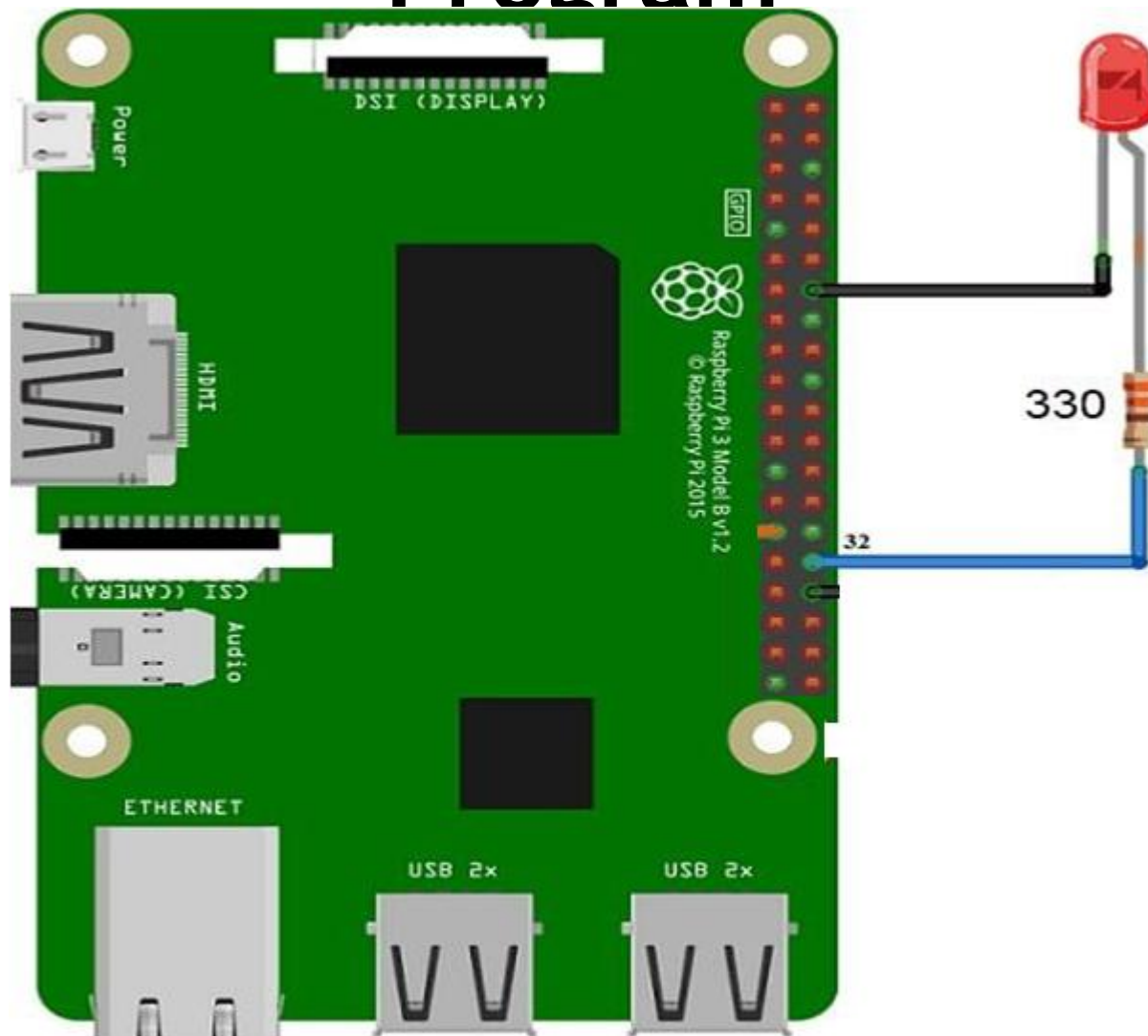
# Functions Used

## 4) **GPIO.output(channel, state)**

- This function is used to set the output state of GPIO pin.
- channel - GPIO pin number as per numbering system.
- state - Output state i.e. HIGH or LOW of GPIO pin

e.g. **GPIO.output(7, GPIO.HIGH)**

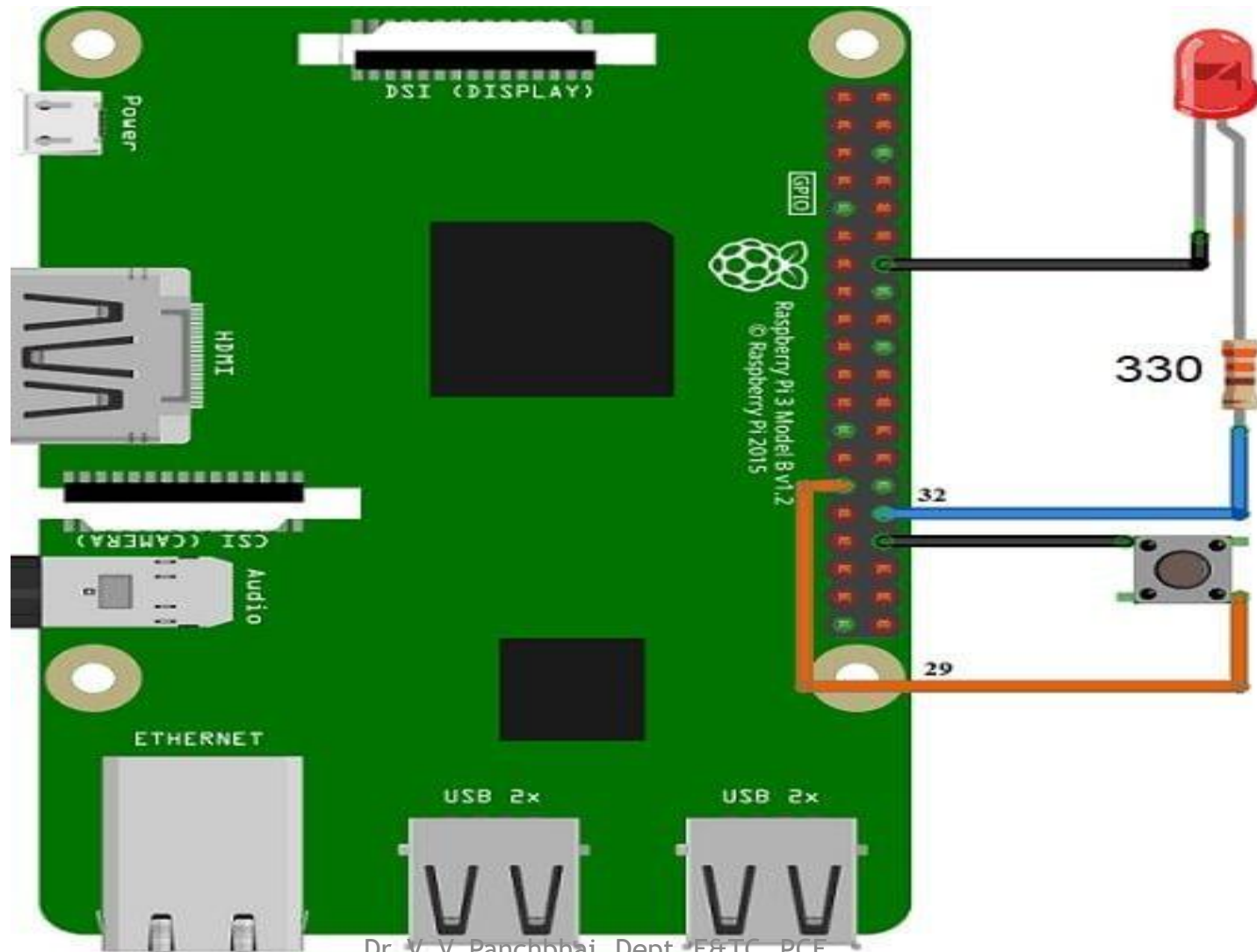
# Interface LED and Write Blink Program



# Program

```
import RPi.GPIO as GPIO
import time
ledpin=12
GPIO.setmode(GPIO.BCM)
GPIO.setwarnings(False)
GPIO.setup(ledpin, GPIO.OUT)
while True:
    GPIO.output(ledpin, GPIO.HIGH)
    print('LED ON')
    time.sleep(1)
    GPIO.output(ledpin, GPIO.LOW)
    print('LED OFF')
    time.sleep(2)
```

# Interface LED and Push Button





# Program

```
import RPi.GPIO as GPIO #import RPi.GPIO module
```

```
LED = 32          #pin no. as per BOARD, GPIO18 as per  
BCM
```

```
Switch_input = 29 #pin no. as per BOARD, GPIO27 as per  
BCM
```

```
GPIO.setwarnings(False) #disable warnings
```

```
GPIO.setmode(GPIO.BOARD) #set pin numbering format
```

```
GPIO.setup(LED, GPIO.OUT) #set GPIO as output
```

```
GPIO.setup(Switch_input, GPIO.IN,  
pull_up_down=GPIO.PUD_UP)
```

```
while True:
```

```
    if(GPIO.input(Switch_input)):
```

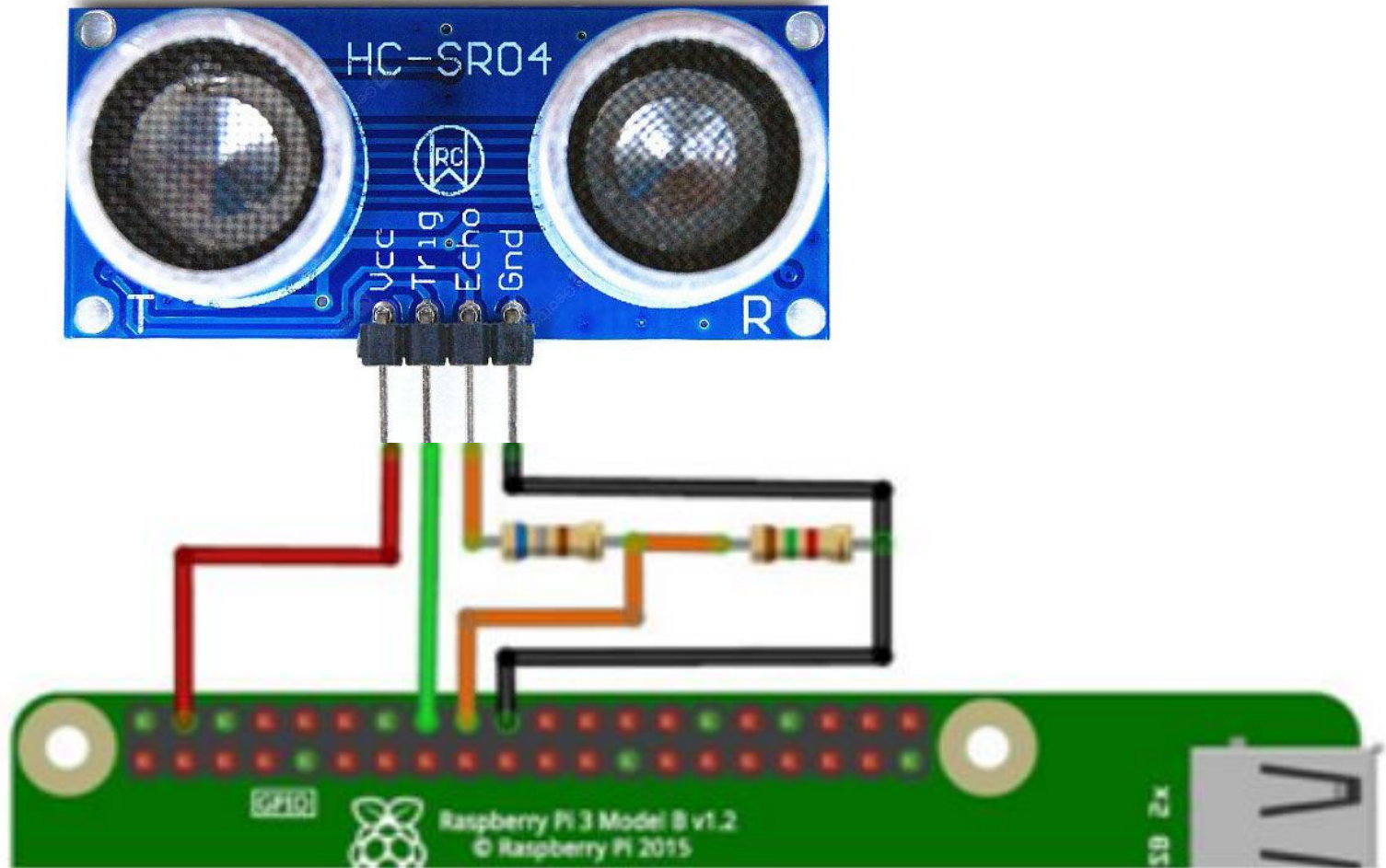
```
        GPIO.output(LED, GPIO.LOW)
```

```
    else:
```

# Interface Picamera and Write Program



# Interface Ultrasonic sensor



# Program

```
from gpiozero import DistanceSensor  
from time import sleep
```

```
GPIO.setmode(GPIO.BCM)  
GPIO.setwarnings(False)
```

```
ultrasonic_sensor = DistanceSensor(echo=5,  
    trigger=6)  
while True:  
    distance= (ultrasonic_sensor.distance*100)  
    print('distance = {0:0.2f} cm'.format (distance))  
    sleep(1)
```

# References

[1]

<https://www.electronicwings.com/raspberry-pi>

[2] [https://www.w3schools.com/nodejs/nodejs\\_raspberrypi.asp](https://www.w3schools.com/nodejs/nodejs_raspberrypi.asp)

[3]

<https://magpi.raspberrypi.com/issues/143/contributions/new>

# Thank You